



## Parallel Robot

# D3PM-25/1200-370

The standard cycle time is less than 0.6s to meet the demand for maximum load and economics.

Rotary servo motor is installed on moving platform to meet the requirements of high-precision rotary operation easily

Widely used in the food and beverage, pharmaceutical, electron, and healthcare industries of heavy workpieces for handling, sorting, measuring, assembling, inspecting, testing and other applications

## SPECIFICATIONS

Robot Version D3PM-25/1200-370

Axes. 3+1

Maximum Payload 25kg

Maximum Working Diameter 1200 mm

Working Height 370 mm

Rotation Angle  $\pm 360^\circ$

Mounting Inverted

Manipulator Weight 143 kg

Angle Range of Active Arm

Upper Arm  $33.8^\circ$

Lower Arm  $87.8^\circ$

Position Repeatability  $\pm 0.05$  mm

Angular Repeatability  $\pm 0.025^\circ$

Max. Load Moment of Inertia  $0.224\text{kg}\cdot\text{m}^2$

Power Requirements

Supply Voltage 220V/380V/3-Phase 220V/1-Phase 49-61 HZ

Rated Power 9.2 kW

Transformer rating 15kVA

Environment Requirements

Storage Temperature  $-10^\circ\text{C}\sim 70^\circ\text{C}$

Working Temperature  $-10^\circ\text{C}\sim 50^\circ\text{C}$

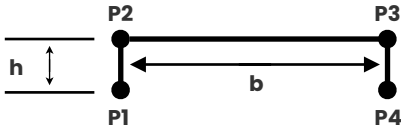
Humidity Range Max. 90%

Protection IP55





## LOAD-FREQUENCY

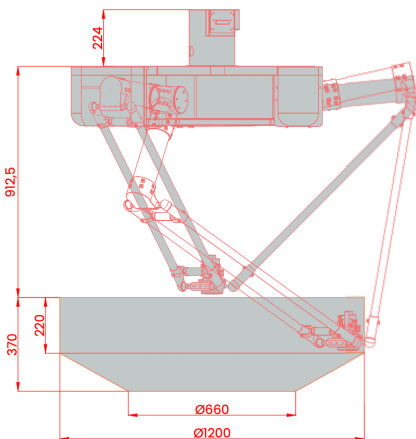


- Trajectory 1  $h=25, b=305$  P1 - P2 - P3 - P4 - P3 - P2 - P1
- Trajectory 2  $h=25, b=305$  P1 - P2 - P3 - P4 - P3 - P2 - P1
- Trajectory 3  $h=25, b=305$  P1 - P2 - P3 - P2 - P1
- Trajectory 4  $h=25, b=305$  P1 - P2 - P3 - P2 - P1

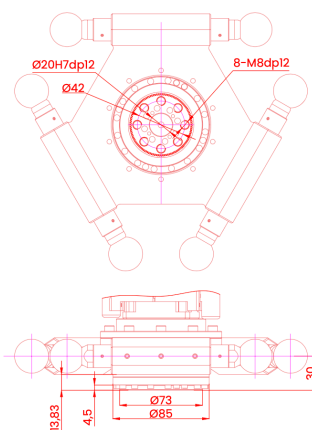
Cycles/min	0.00kg	3.00kg	6.00kg	9.00kg	12.00kg	15.00kg	18.00kg	21.00kg	25.00kg
Trajectory 1	117.00	104.00	91.00	78.00	78.00	71.50	65.00	58.5	58.5
Trajectory 2	104.00	91.00	78.00	65.00	65.00	58.50	52.00	45.5	45.5
Trajectory 3	134.55	119.60	104.65	89.70	89.70	82.23	74.75	67.275	67.275
Trajectory 4	114.40	100.10	85.80	71.50	71.50	64.35	57.20	50.05	50.05

The cycle times are measured under real conditions, but may vary depending on the actual application.

### Dimensions & Range of Motion(mm)



### Flange(mm)



### Mounting Base(mm)

